Rainer Grimm Training, Mentoring, and Technology Consulting

Definition

"Each pattern is a three-part rule, which expresses a relation between a certain context, a problem, and a solution." (Christopher Alexander)

Three Types of Patterns

- Architecture pattern
 - Fundamental structure
 - Software system
- Design pattern
 - Interplay of components
 - Focus on a subsystem
- Idiome
 - Implementation of an architecture or design pattern in a programming language.

Components of a Pattern

- 1. Name
- 2. Also known as
- 3. Summary
- 4. Motivation
- 5. Context
- 6. Interaction
- 7. Solution
- 8. Example
- 9. Consequenses
- 10.Related pattern
- 11.Known usages

Pattern-Oriented Software Architecture (Volume 2 and 4)

Concurrent Programming in Java





Concurrent Programming in Java[™] **Second Edition Design Principles and Patterns**

Doug Lea



LAVA LAVA





Copied Value

There is no need to synchronize when a thread takes its arguments by copy and not by reference.



Thread-Specific Storage

Thread-specific storage enables global state within a thread.

- Typical use-cases
 - Porting a single-thread to multithreaded program
 - Compute thread-local and publish the result
 - Thread-local logger

Future

A future is a non-mutable placeholder for a value, which is set by a promise.

```
auto future = std::async([] { return "LazyOrEager"; });
future.get();
```

Promise: sender Future: receiver





Scoped Locking

Scoped Locking is RAII applied to locking.

- Idea
 - Bind the acquiring (constructor) and the releasing (destructor) of the resource to the lifetime of an object.
 - The lifetime of the object is scoped.
 - The C++ run time is responsible for invoking the destructor and releasing the resource.

C++ Implementation

- std::lock_guard and std::scoped_lock
- std::unique_lock and std::shared_lock



Strategized Locking

Strategized Locking

- Enables it to use various locking strategies as replaceable components.
- Is the application of the strategy pattern to locking.

- Idea
 - You want to use your library in various domains.
 - Depending on the domain, you want to use exclusive locking, shared locking, or no locking.
 - Configure your locking strategy at compile time or run time.

Strategized Locking

Advantages:

Run-time polymorphism

- Enables it to change the locking strategy at runtime.
- Compile-time polymorphism
 - No cost at runtime
 - Flatter object hierarchies

Disadvantages:

- Run-time polymorphism
 - Needs a pointer indirection.

- Compile-time polymorphism
 - Produces in the error case a quite challenging to understand error message (when no concepts are used).

strategizedLockingRuntime.cpp
strategizedLockingCompileTimeWithConcepts.cpp

Thread-Save Interface

The thread-save interface extends the critical region to an object.

- Antipattern: Each member function uses a lock internally.
 - The performance of the system goes down.
 - Deadlocks appear when two member functions call each other.

Thread-Save Interface

A deadlock due to entangled calls.

```
struct Critical{
    void method1() {
        std::lock guard l(mut);
                                      int main() {
        method2();
                                           Critical crit;
        • • •
                                           crit.method1();
    void method2() {
        std::lock guard l(mut);
         • • •
    std::mutex mut;
```

Thread-Save Interface

Solutions:

- All interface member functions (public) use a lock.
- All implementation member functions (protected and private) must not use a lock.
- The interface member functions call only implementation member functions.

Guarded Suspension

A guarded suspension consists of a lock and a condition. The condition has to be fulfilled by the calling thread.

- The calling thread will put itself to sleep if the condition is not meet.
- The calling thread uses a lock when it checks the condition.
- The lock protects the calling thread from a data race or deadlock.

Guarded Suspension

- Guarded suspension enables thread synchronization. It is available in many variations.
 - The waiting thread is notified about the state change or asks for the state change.
 - Push principle: condition variables, future/promise pairs, atomics, latches and barriers, or semaphores
 - Pull principle: not natively supported in C++
 - The waiting thread waits with or without a time limit.
 - Condition variables, or future/promise pairs
 - The notification is sent to one or all waiting threads.
 - Shared futures, condition variables, atomics, latches and barriers, or semaphores

bossWorkerFuturePromise.cpp bossWorkerLatch.cpp



The active object pattern separates the method execution from the method invocation.

- Each object owns its own thread.
- Each method invocation is stored in an activation list.
- A scheduler triggers the method execution.

Proxy:

- Proxy for the member functions on the active object
- Triggers the construction of a request object which goes to the activation list and returns a future.
- It runs in the client thread.

Method Request

Includes all context information to be executed later.

Activation List:

- Has the pending requests objects.
- Decouples the client from the Active Object thread.

Scheduler:

- Runs in the thread of the Active Object.
- Decides with request from the Activation List is executes.

- Servant:
 - Implements the member functions of the active objects.
 - Supports the interface of the Proxy.
- Future:
 - Is created by the Proxy.
 - Is only necessary if the request objects returns a result.
 - The client uses the future to get the result of the request object.

Dynamic Behavior

- 1. Request construction and scheduling:
 - The client invokes the method on the proxy.
 - The proxy creates a request and passes it to the scheduler.
 - The scheduler enqueues the request on the activation list and returns a future to the client if the request returns something.
- 2. Member function execution
 - The scheduler determines which request becomes runnable.
 - It removes the request from the activation list and dispatches it to the servant.
- 3. Completion:
 - Stores eventually the result of the request object in the future.
 - Destructs the request object and the future if the client has the result.



Advantages:

- Only the access to the activation list has to be synchronized
- Clear separation of client and server
- Improved throughput due to the asynchronous execution
- The scheduler can use various execution policies.

Disadvantages:

- If the member function execution is too fine-grained, the indirection may cause significant overhead.
- The asynchronous member function execution and the various execution strategies make the system quite difficult to debug.

Synchronization Concurrent Architecture Patterns **Dealing with Sharing** Active Object Copied Value Thread-Specific Storage Futures Monitor Object **Dealing with Mutation** Scoped Locking Strategized Locking Thread-Safe Interface

Guarded Suspension

The monitor object synchronizes the access to an object so that at most one member function can run at any time.

- Each object has a monitor lock and a monitor condition.
- The monitor lock guarantees that only one client can execute a member function of the object.
- The monitor condition notifies the waiting clients.



Monitor Object:

• Support member functions, which can run in the thread of the client.

Synchronized Methods:

- Interface member functions of the monitor object.
- At most, one member function can run at any time
- The member functions should apply the thread-safe interface pattern.

Monitor Lock:

- Each monitor object has a monitor lock.
- Guarantees exclusive access to the member functions.

Monitor Condition:

- Allows various threads to store their member function invocation.
- When the current thread is done with its member function execution, the next thread is awoken.

Advantages:

- The synchronization is encapsulated in the implementation.
- The member function execution is automatically stored and performed.
- The monitor object is a simple scheduler.

Disadvantages:

- The synchronization mechanism and the functionality are strongly coupled and can, therefore, not easily be changed.
- When the synchronized member functions invoke an additional member function of the monitor object, a deadlock may happen.



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